



NHTSA's Light Vehicle ESC Research Program

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Effectiveness of Electronic Stability Control for Preventing Crashes

ESC Effectiveness

- **Multiple studies have been conducted**
- **Europe**
 - DaimlerChrysler
 - Swedish Nat. Road Administration
 - European Accident Causation Survey
- **Japan**
 - Toyota
- **United States**
 - NHTSA
 - IIHS

- **German crash data**
 - German Government Statistics Office (Statistischen Bundesamtes)
 - 1999/2000 data compared to 2000/2001
 - Newly registered Mercedes vehicles
 - ESC standard equipment for MY1999
- **Estimates based on statistical analyses**
 - 15% reduction in total accidents
 - 30% reduction in single vehicle accidents
- **Reductions in side-impacts, rollover crashes, and average injury severity**

- **Swedish crash data**
 - Police reported accidents with at least one injured person
 - Accidents occurred during 2000 to 2002
 - Cars of similar/identical make model were used; 1998 to 2003 model years
- **ESC effectiveness estimates based on statistical analyses**
 - Dry roads: No significant effect
 - Wet roads: At least a 7.8% reduction*
 - Snow / Ice: At least a 12.1% reduction*
- **Most significant accident reduction observed for large cars (both front- and rear-wheel drive), especially on low-mu surfaces**

**Lower bound of the 95% confidence limit*

European Accident Causation Survey

(Sferco, et al.)

- **Potential ESC effectiveness based on statistical analyses of EACS data (i.e., the “opportunity” for ESC to improve safety)**
- **EACS contains data from approximately 1674 crashes in 5 European countries from 1995 to 1999**
- **Expert EACS investigators believe the presence of ESC could have improved the outcome of many accidents investigated**
 - **Injury accidents: 18%**
 - **Fatal accidents: 34%**
- **If accident causation was “loss of vehicle control”, the benefits of ESC are expected to be even more apparent**
 - **Injury accidents: 42%**
 - **Fatal accidents: 67%**

- **Japanese crash data**
 - Compiled by the Institute for Traffic Accident Research and Data Analysis (ITARDA)
 - 3 popular Toyota passenger cars were considered
- **Estimates based on statistical analyses**
 - 35% reduction in single car accidents
 - 30% reduction in head-on collisions with other vehicles
 - 35% reduction in casualties per year
(for single car crashes and head-on collisions)
- **ESC effectiveness appears to be highest in the range of approximately 40 - 100 kmph (25 – 75 mph)**

- **Examined single vehicle crashes**
 - Limited number of higher end vehicles
- **Two sources of data**
 - State data for all crash severities for five states (1997 – 2002)
 - FARS data (1997 –2003)
- **All severities of single vehicle crashes reduced**
 - Passenger cars: 35%
 - Sport utility vehicles: 67%
- **Fatal single vehicle crashes reduced by:**
 - 30% for passenger cars
 - 63% for sport utility vehicles

- **Calculated fatal crash risk per registered vehicle for vehicles with ESC standard versus those with no ESC or ESC optional**
- **Found that:**
 - Fatal single vehicle crash risk reduced by 56%
 - Multi-vehicle fatal crash risk reduced by 17%
 - Risk for all fatal vehicle crashes reduced by 34%
- **If ESC present on all light vehicles, it could**
 - Prevent 800,000 single vehicle crashes per year
 - Saving 7,000 lives per year

ESC Effectiveness - Summary

- **Multiple studies, in several countries using different data sets and methodologies, have all found substantial reduction in single vehicle crashes due to ESC**
 - Typically about a 30% reduction
- **Each study indicates installation of ESC on all light vehicles should prevent many fatal crashes each year**



How Does Electronic Stability Control Prevent Crashes?

How ESC Helps: Untripped Rollover Reduction

- **Test using NHTSA Fishhook**
- **ESC can be tuned to prevent two wheel lift in NHTSA Fishhook**
 - Not all tunings will prevent untripped rollover
 - Requires aggressive front wheel braking
- **Untripped rollovers represent a small percentage of the rollover crash problem**

How ESC Helps: Transient Oversteer Reduction

- **Test using variant of single sine steer**
 - Will discuss test in greater detail later
 - NHTSA has selected
- **Thought to be important mechanism for prevention of crashes**
 - Approximately 25% of fatal single vehicle crashes believed to be due to transient oversteer

Example:

Transient Oversteer (disabled ESC)

2004 Volvo XC 90
ESC Disabled
SWA = 130 degrees

Example:

Effect of ESC (enabled ESC)

2004 Volvo XC 90
ESC Enabled
SWA = 300 degrees

How ESC Helps: Excessive Understeer Reduction

- **Do not know how to test for excessive transient understeer**
 - Plan to develop test in future
- **Thought to be important mechanism for mitigation or prevention of crashes**
 - Magnitude of effect not known

How ESC Helps: Slows Vehicle Down

- **ESC gets brakes on in emergency situations**
 - Generally, this is better than not braking
- **ESC may also “pre-charge” a vehicle’s brakes**
 - Low pressure brake application
 - Gets brakes on 0.10 to 0.15 seconds faster if needed
- **Thought to be important mechanism for mitigation or prevention of crashes**
 - Even small amount slowing down can mitigate or prevent some crashes
 - Magnitude of effect not known

How ESC Helps:

- **We do not have complete answer to question of how ESC helps**
- **Remains active research topic**



Current NHTSA ESC Research Program

Program Objectives

- **Develop test to ensure that vehicle does not go out of control (spinout) due to transient oversteer**
 - Objective satisfied, will discuss later
- **Develop pass/fail criteria**
- **Prevention of excessive understeer will be worked upon later**
- **May or may not want to do further research on how ESC helps slow vehicles down**

Program Approach

- **Building on non-linear handling research performed by Alliance of Automobile Manufacturers**
- **NHTSA is collaboratively gathering data to improve proposed test to ensure that vehicle does not spinout due to transient oversteer**
 - **Presently refining pass/fail criteria**

Five Maneuvers

Performed With A Steering Machine

- **Slowly Increasing Steer**
(for characterization use only)
- **0.7 Hz Sine with Dwell**
- **0.7 Hz Increasing Amplitude Sine**
- **500 deg/s Yaw Acceleration Steering Reversal**
- **500 deg/s Yaw Acceleration Steering Reversal w/Pause**

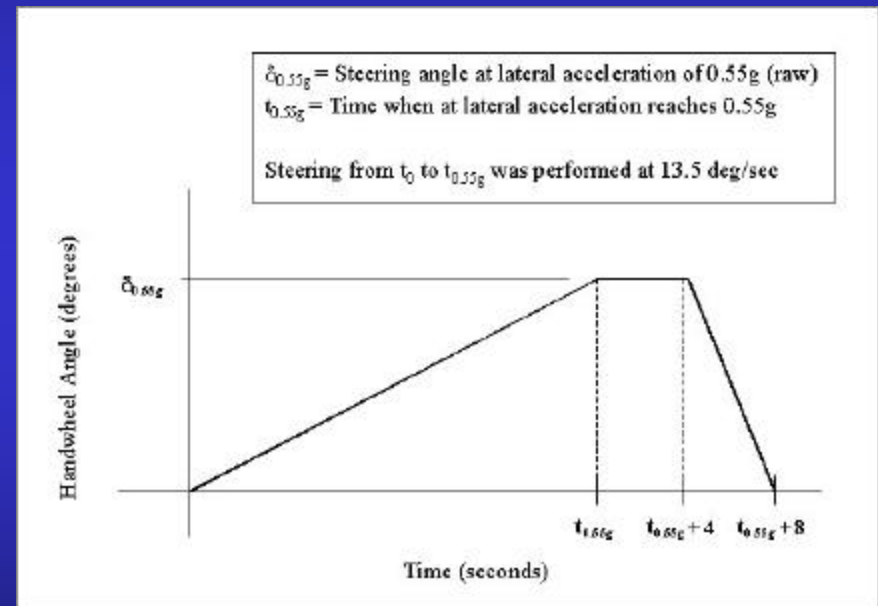
Test Conditions

- **ESC enabled and disabled**
- **Test surface**
 - Dry, high-mu asphalt
 - Maneuvers initiated while vehicle is being driven up a 1% grade
- **Nominal load**
 - Driver
 - Instrumentation
 - Outriggers if vehicle is an SUV, pickup, van, minivan, station wagon, or crossover vehicle

Maneuver Description

Slowly Increasing Steer

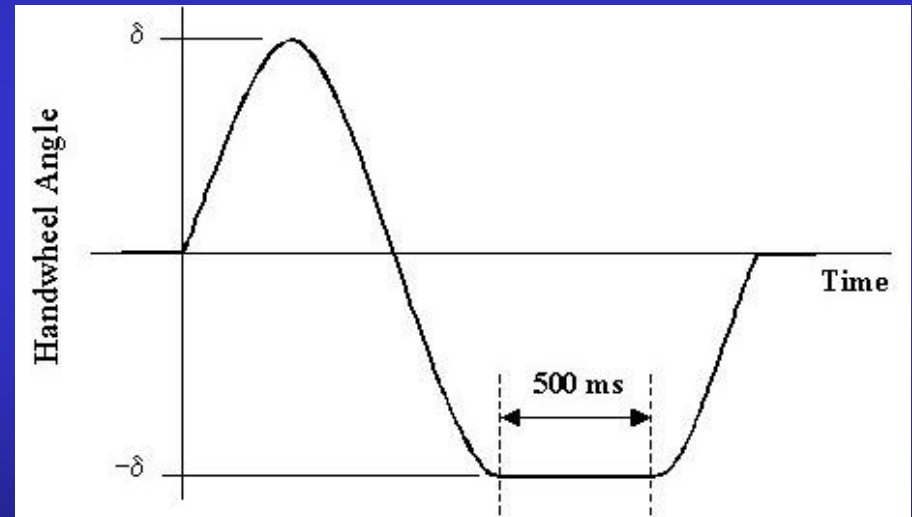
- **Low severity**
 - Used for characterization only
 - Raw AY of 0.55g
- **Provides the SWA at 0.3g**
 - Data is required by all other maneuvers performed in this study
 - Must first be corrected for roll effects
- **Driver attempts to maintain constant vehicle speed via throttle modulation**
 - 50 mph



Maneuver Description

0.7 Hz Sine with Dwell

- Steering frequency fixed at 0.7 Hz, but with a 500 ms pause after the 3rd quarter-cycle
- Severity increased with SWA
 - Increments of $1.0 * d_{0.3g \text{ AY from SIS}}$
 - Lowest SWA: $1.5 * d_{0.3g \text{ AY from SIS}}$
 - Highest SWA: 270 deg or $6.5 * d_{0.3g \text{ AY from SIS}}$ whichever is greater
- 50 mph entrance speed
- Dropped throttle

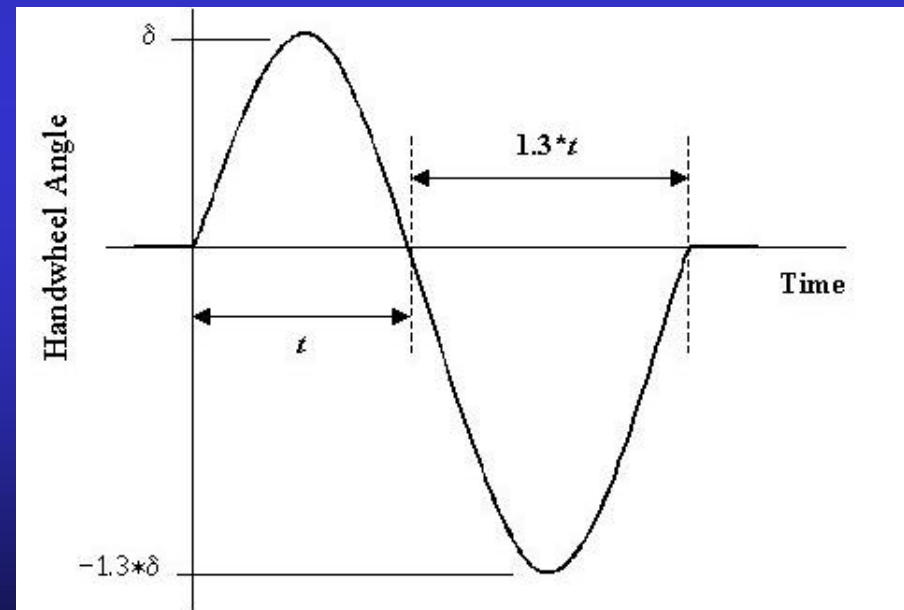


Maneuver Description

0.7 Hz Increasing Amplitude Sine

- Steering of frequency first $\frac{1}{2}$ cycle fixed at 0.7 Hz
- 2nd $\frac{1}{2}$ cycle amplitude is 1.3 times that of the 1st $\frac{1}{2}$ cycle
- Duration of the 2nd $\frac{1}{2}$ cycle is 1.3 times that of the 1st $\frac{1}{2}$ cycle
- Severity increased with SWA
 - Increments of $1.0 * d_{0.3g \text{ AY from SIS}}$
 - Lowest 2nd Steer SWA:
 $1.5 * d_{0.3g \text{ AY from SIS}}$
 - Highest 2nd Steer SWA:
270 deg or $6.5 * d_{0.3g \text{ AY from SIS}}$
whichever is greater

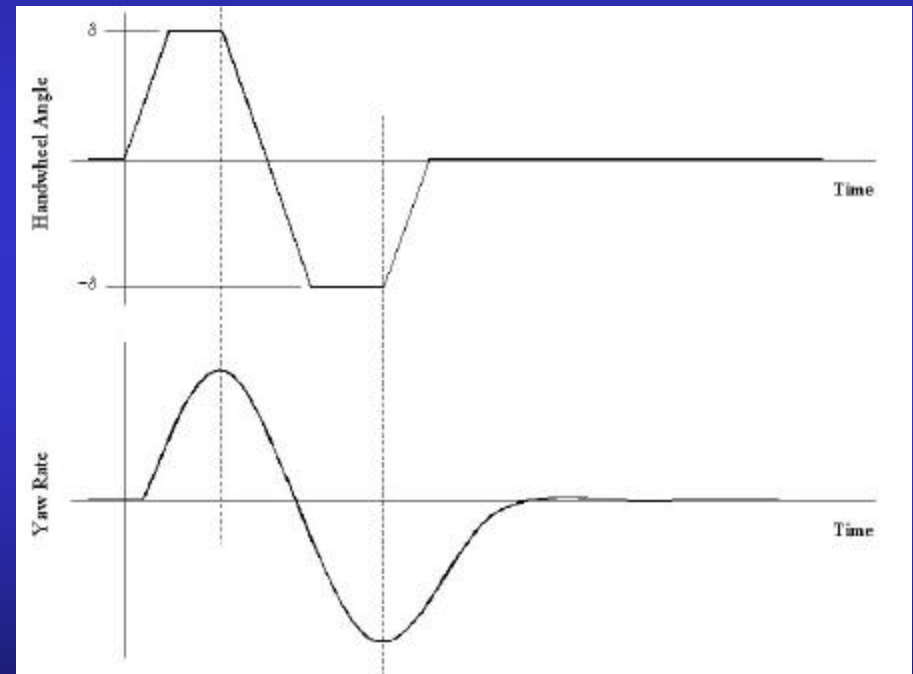
- 50 mph entrance speed
- Dropped throttle



Maneuver Description

Yaw Acceleration Steering Reversal

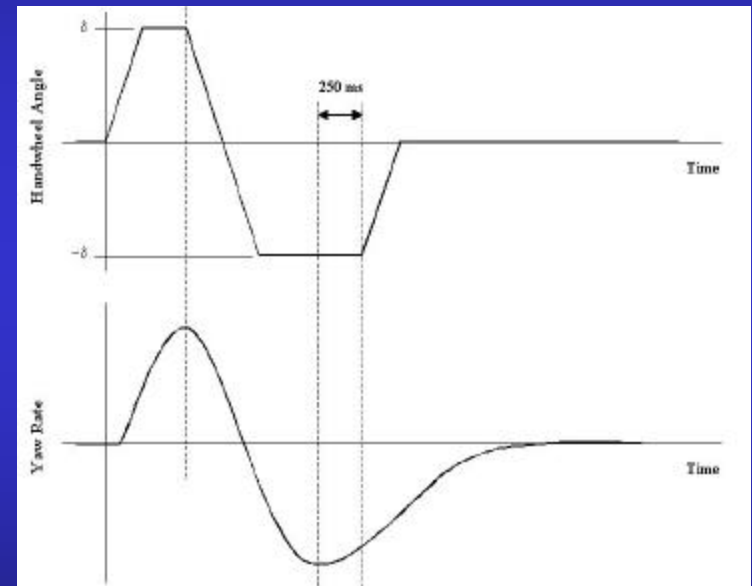
- Maneuver adapts to the vehicle being evaluated rather than relying on one frequency
- Steering reversals both initiated at peak yaw rate
- Severity increased with SWA
 - Increments of $1.0 * d_{0.3g \text{ AY from SIS}}$
 - Lowest SWA: $1.5 * d_{0.3g \text{ AY from SIS}}$
 - Highest SWA: 270 deg or $6.5 * d_{0.3g \text{ AY from SIS}}$ whichever is greater
 - 500 deg/s ramp rates



Maneuver Description

Yaw Accel Steering Reversal w/Pause

- Maneuver adapts to the vehicle being evaluated rather than relying on one frequency
- 1st steering reversal initiated at peak yaw rate, 2nd reversal at peak yaw rate + 250 ms
- Increased dwell after second yaw rate peak gives the vehicle more time to respond to the second peak SWA
- Severity increased with SWA
 - Increments of $1.0 * d_{0.3g \text{ AY from SIS}}$
 - Lowest SWA: $1.5 * d_{0.3g \text{ AY from SIS}}$
 - Highest SWA: 270 deg or $6.5 * d_{0.3g \text{ AY from SIS}}$ whichever is greater
 - 500 deg/s ramp rates



Program Approach

- Each of these maneuvers has advantages and disadvantages
 - Much emphasis was placed on better understanding these factors for each maneuver
- Recently, the “Sine with Dwell” was selected as NHTSA’s preferred test maneuver
- Results from NHTSA and industry indicate this maneuver offers the best combination of severity, performability, and repeatability for a broad range of vehicles

2005 Testing

- **Evaluate 50 vehicles in 2005**
 - NHTSA: 24 vehicles
 - Industry: 26 vehicles
- **Vehicles separated into two groups**
 - Priority #1
 - Priority #2
- **Data from “Priority #1” vehicles presently being analyzed**
- **NHTSA hopes to have a more well-defined pass/fail criteria by July 1, 2005**

Pass/Fail Criteria

- **Spinout must not occur**
 - Need definition of spinout
- **Vehicle must still be responsive**
 - E.g., Must achieve a minimum lateral displacement during test
 - Proposed magnitude: 12-feet
- **No two-wheel lift**
- **No tire debanding or rim-to-pavement contact**

What is a “Spinout”

- **NHTSA does not know of a generally accepted, quantitative definition**
- **People generally know spinout when they see it**
- **However, there are some vehicles/cases which are not clear**

What is a “Spinout”



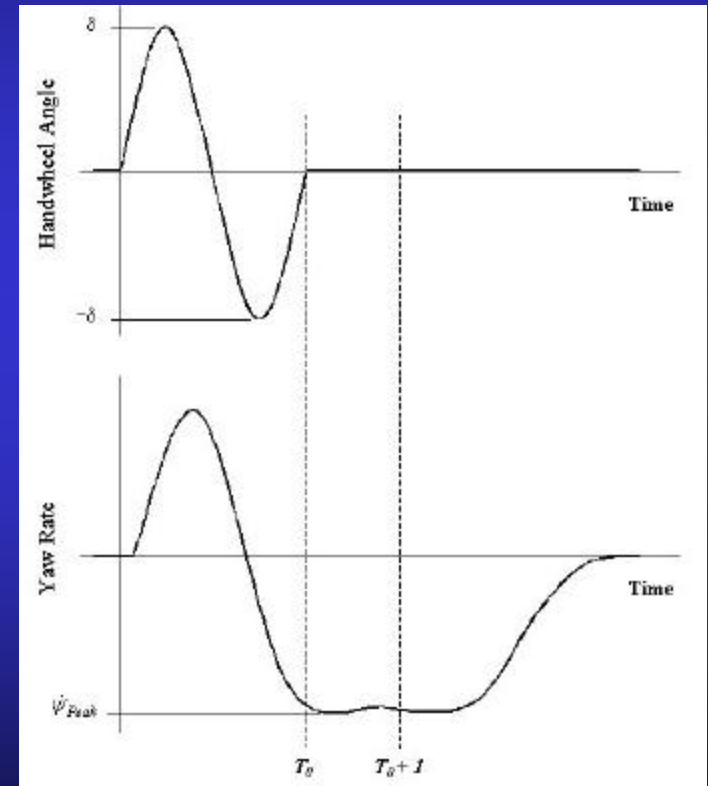
What is a “Spinout”

Preliminary NHTSA Definition

$$\text{Percent } \dot{y}_{Peak} = 100 * \left(\frac{\dot{y}(t)}{\dot{y}_{Peak}} \right)$$

Set $t = t_0 + 1$

Spinout occurs if $\text{Percent } \dot{y}_{Peak} \geq 60\%$



What is a “Spinout”

- Other people/organizations are developing alternative definitions of spinout
 - NHTSA welcomes alternate definitions!
- Will pick the best, most robust definition from among those suggested

Additional Information on NHTSA's Research

- **ESC Docket**

- <http://dms.dot.gov/search/searchFormSimple.cfm>
- Number 19951

- **VRTC ESC Website**

- <http://www-nrd.nhtsa.dot.gov/vrtc/ca/esc.htm>